

# A two-layer solid/liquid mixture model for fluidized granular flows with dilatancy effects

F. Bouchut<sup>1</sup>, A. Mangeney<sup>2</sup>, E.D. Fernandez-Nieto<sup>3</sup>, G. Narbona-Reina<sup>3</sup>

<sup>1</sup>*LAMA, CNRS & Université Paris-Est*

<sup>2</sup>*IPGP & Université Paris-Diderot*

<sup>3</sup>*Universidad de Sevilla*

Bordeaux, January 12 2016



- 1 *Viscoplastic materials*
- 2 *Dilatancy*
- 3 *Thin layer approximations*
- 4 *Jackson's two-phase model*
- 5 *Two-phase two-layer model with dilatancy*

Viscoplastic materials are characterized by

- Nonlinear relation between stress and strain rate (non-Newtonian fluid)
- Irreversible deformations inducing dissipation



Examples of such materials : snow, mud, lava, **grains in a surrounding fluid (wet sand)**.  
Behaviour can be fluid or solid

Momentum equation for an **incompressible** ( $\operatorname{div} u = 0$ ) **viscoplastic material** :

$$\partial_t u + u \cdot \nabla u - \operatorname{div} \sigma = f,$$

where the **stress**  $\sigma$  is related to the **strain rate**  $Du = (\nabla u + (\nabla u)^t)/2$  by a nonlinear relation

$$\sigma = -p \operatorname{Id} + \sigma', \quad \sigma' = F(Du),$$

with  $F$  a monotone nonlinearity (that defines the **rheology**).

- For a Bingham fluid

$$F(Du) = \kappa \frac{Du}{\|Du\|},$$

for some constant  $\kappa$  (**yield stress**). Multivalued meaning :

$$\begin{cases} \|\sigma'\| \leq \kappa, \\ Du \neq 0 \text{ implies } \sigma' = \kappa \frac{Du}{\|Du\|}. \end{cases}$$

Where  $Du = 0$ , the material is solid.

- $\mu(I)$  rheology (Jop, Forterre, Pouliquen 06)

$$\sigma' = \mu(I) p \frac{Du}{\|Du\|},$$

with  $I = 2d\|Du\|/\sqrt{p/\rho_s}$ ,  $d$  diameter of the grains,  $\rho_s$  density of the solid.

- **No justification from microscopic (anelastic) laws, just scaling laws!**

We consider a **dry** granular material. The only non Newtonian effect that we take into account is **dilatancy**.

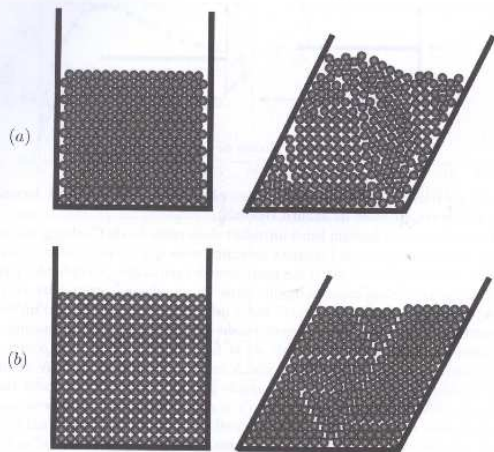


FIG. 4.9 – (a) Dilatance observée lorsqu'on cisaille un empilement bidimensionnel triangulaire. (b) Contractance observée lorsqu'on cisaille un empilement carré (dessins inspirés d'expériences de Brown & Richards, 1970).

Figures from "Les milieux granulaires",  
B. Andreotti, Y. Forterre, O. Pouliquen

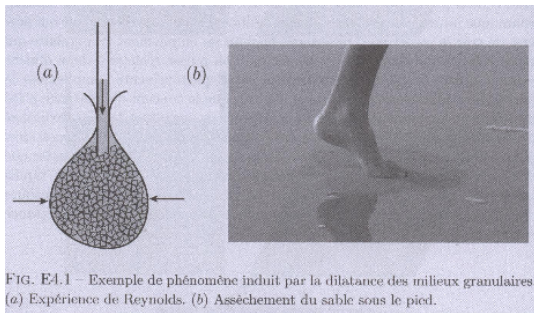
(a) The material dilates  
when deformed

(b) The material contracts  
when deformed

**Relation between deformation and  
dilation/contraction !**

We consider a **wet** granular material.

Figures from "Les milieux granulaires", B. Andreotti, Y. Forterre, O. Pouliquen



- (a), (b) When a **dense** packing of sand is deformed, the granular material **dilates**, and water is **sucked**
- When a **loose** packing of sand is deformed, the granular material **contracts**, and water is **expelled** (ex : landslide, quicksand "sables mouvants").

Great open problems :

- Write a geophysically and mathematically relevant rheology for **compressible viscoplastic materials** !
- Derive (even formally!) viscoplastic laws from a microscopic description

### Basis of classical thin layer approximations :

- Saint Venant (shallow water) model derived from **incompressible Euler equations** above an almost flat topography
- Savage, Hutter (1989) take into account the bottom friction and main curvature,
- Submerged flows models proposed by Iverson, Denlinger (2001), Pitman, Le (2005), Pailha, Pouliquen (2009), Iverson, George (2014)

### Difficulties :

- Complex rheology not taken into account in the above expansions, but only dilatancy effects.
- Physics of diphasic mixtures is involved. Dilatancy laws are not obvious to set.

### Benefits :

- Replace viscoplastic laws by boundary friction
- Less space variables is better for simulation

### In this talk :

- Use asymptotic expansions as far as possible without introducing heuristic rules.
- Keep the mathematical structure to avoid unphysical effects. In particular, keep an energy balance.

We consider a wet granular material. The features to take into account are

- buoyancy force
- interphase friction force (*drag*)
- solid (granular) pressure and pore (fluid) pressure, both non hydrostatic because of the relative interphase velocity
- Dilatancy : the granular material dilates if its volume fraction is larger than a critical value, or contracts in the opposite case. In the first case the granular friction increases (stiffening of the granular matrix). In the second case the granular friction diminishes (fluidisation). Law proposed by Roux and Radjai (1998).



Jackson's model can be written as follows.

- Two mass equations

$$\begin{aligned}\partial_t(\rho_s\varphi) + \nabla \cdot (\rho_s\varphi\mathbf{v}) &= 0, \\ \partial_t(\rho_f(1-\varphi)) + \nabla \cdot (\rho_f(1-\varphi)\mathbf{u}) &= 0,\end{aligned}$$

with  $\rho_s$ ,  $\rho_f$  the (constant) solid/fluid mass densities,  $\varphi$  the solid volume fraction,  $\mathbf{v}$  the solid velocity, and  $\mathbf{u}$  the fluid velocity.

- Two momentum equations

$$\begin{aligned}\rho_s\varphi(\partial_t\mathbf{v} + \mathbf{v} \cdot \nabla\mathbf{v}) &= -\nabla \cdot \mathbf{T}_s - \varphi\nabla p_{f_m} + \mathbf{f} + \rho_s\varphi\mathbf{g}, \\ \rho_f(1-\varphi)(\partial_t\mathbf{u} + \mathbf{u} \cdot \nabla\mathbf{u}) &= -\nabla \cdot \mathbf{T}_{f_m} + \varphi\nabla p_{f_m} - \mathbf{f} + \rho_f(1-\varphi)\mathbf{g},\end{aligned}$$

where  $\mathbf{g}$  is gravity,  $\mathbf{f}$  is the drag force

$$\mathbf{f} = \tilde{\beta}(\mathbf{u} - \mathbf{v}), \quad \tilde{\beta} = \frac{18\nu_f\rho_f\varphi}{d^2}$$

with  $\nu_f$  the fluid viscosity and  $d$  the diameter of the grains.

- $\mathbf{T}_s$ ,  $\mathbf{T}_{f_m}$  are the solid and fluid stress tensors, taken as

$$\mathbf{T}_s = p_s\mathbf{I}d + \tilde{\mathbf{T}}_s, \quad \mathbf{T}_{f_m} = p_{f_m}\mathbf{I}d + \tilde{\mathbf{T}}_{f_m},$$

with  $\tilde{\mathbf{T}}_k$  small far from shearing boundary layers.

Unknowns in Jackson's model :

- 5 unknowns :  $\varphi$ ,  $v$  (vector),  $u$  (vector),  $p_s$ ,  $p_{fm}$
- 4 equations (2 vectors)

A constitutive equation is required to close the system : dilatancy law

The only non Newtonian effects that we take into account result from dilatancy.

## Qualitative explanation of dilatancy effects

$$\varphi < \varphi_c \text{ (loose)}$$

Granular medium **contracts**  
when deformed



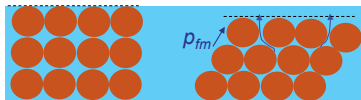
Water must be expelled



**Increasing** pore pressure



**Liquefaction**



$$\varphi > \varphi_c \text{ (dense)}$$

Granular medium **dilates**  
when deformed



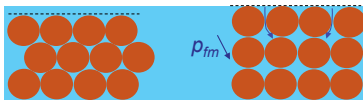
Water must be sucked



**Decreasing** pore pressure



**Stiffening of the granular matrix**



*Pailha and Pouliquen, 2009; Y. Forterre, Seville 2014*

## Modeling of dilatancy effects

- Compression/dilatation of the solid phase :

$$\nabla \cdot v = \dot{\gamma} \tan \psi \quad \text{Roux and Radjai, 1998}$$

$\psi$  : dilatancy angle,  $\dot{\gamma}$  : shear strain rate

$$\tan \psi = K(\varphi - \varphi_c) \quad \text{Pailha and Pouliquen, 2009}$$

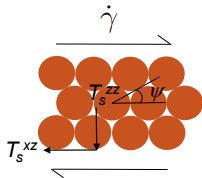
→ Closure equation :  $\nabla \cdot v = K\dot{\gamma}(\varphi - \varphi_c)$

$\varphi < \varphi_c$  : compression

$\varphi > \varphi_c$  : dilatation

- Impact of the dilatancy angle on the **Coulomb friction force** :

$$T_s^{xz} = - \tan(\delta + \psi) \text{sign}(v) T_s^{zz}$$



- With a slightly modified Roux-Radjai closure, Jackson's system has a relevant **energy equation**

$$\begin{aligned} & \partial_t \left( \rho_s \varphi \frac{|v|^2}{2} + \rho_f (1 - \varphi) \frac{|u|^2}{2} - (\mathbf{g} \cdot X) (\rho_s \varphi + \rho_f (1 - \varphi)) + \rho_s \varphi e_c \right) \\ & + \nabla \cdot \left( \rho_s \varphi \frac{|v|^2}{2} v + \rho_f (1 - \varphi) \frac{|u|^2}{2} u - (\mathbf{g} \cdot X) (\rho_s \varphi v + \rho_f (1 - \varphi) u) \right. \\ & \quad \left. + p_{f_m} (\varphi v + (1 - \varphi) u) + \tilde{T}_{f_m} u + T_s v + \rho_s \varphi e_c v \right) \\ & = (p_s - p_c) \nabla \cdot v + \tilde{T}_s : \nabla v + \tilde{T}_{f_m} : \nabla u + f \cdot (v - u). \end{aligned}$$

with  $X$  the space position, and the closure is taken as

$$\nabla \cdot v = K_p \dot{\gamma} (p_c(\varphi) - p_s)$$

with  $p_c(\varphi)$  the **critical pressure**, and  $e_c(\varphi)$  the critical specific internal energy defined by  $de_c/d\varphi = p_c/(\rho_s \varphi^2)$ .

- The right-hand side of the energy balance equation is nonpositive
- The closure law can be interpreted as a **compressible bulk viscoplastic rheology**

$$p_s = p_c(\varphi) - \frac{\nabla \cdot v}{K_p \dot{\gamma}},$$

with  $\dot{\gamma} = \|Dv\|$ ,  $Dv = (\nabla v + (\nabla v)^t)/2$ .

Bouchut, Fernandez-Nieto, Mangeney, Narbona-Reina (2015).

- Two thin layers : one layer of solid/fluid mixture (volume fraction  $0 < \varphi < 1$ ) treated via Jackson's model, and one layer of pure fluid above

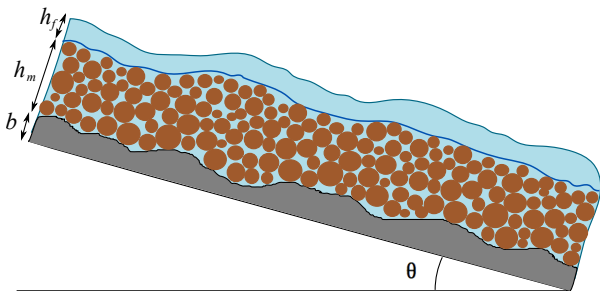


FIG.: Two-layer configuration

- The fluid can enter or get out of the mixture when the granular medium dilates or contracts
- In contrast with all previously proposed models, we have  $h_f > 0$ , and two unknown velocities (one for the solid and one for the fluid) instead of one.
- Suitable boundary conditions have to be set.

- **At the bottom** we put non penetration conditions

$$u \cdot n = 0, \quad v \cdot n = 0,$$

a solid Coulomb friction law

$$(T_s n)_\tau = -\tan \delta_{\text{eff}} \frac{v}{|v|} (T_s n) \cdot n,$$

and a Navier friction condition for the fluid phase

$$(T_{f_m} n)_\tau = -k_b u.$$

- **At the free surface** we assume no tension for the fluid

$$T_f N_X = 0,$$

together with the kinematic condition

$$N_t + u_f \cdot N_X = 0,$$

where  $N = (N_t, N_X)$  is a time-space normal to the free surface.

- At the interface, we have the kinematic condition for the solid phase

$$\tilde{N}_t + v \cdot \tilde{N}_X = 0,$$

where we denote by  $\tilde{N} = (\tilde{N}_t, \tilde{N}_X)$  a time-space upward normal to the interface. The total fluid mass is conserved,

$$\tilde{N}_t + u_f \cdot \tilde{N}_X = (1 - \varphi^*)(\tilde{N}_t + u \cdot \tilde{N}_X) \equiv \mathcal{V}_f$$

where  $\varphi^*$  is the value of the solid volume fraction at the interface (the limit is taken from the mixture side). The term  $\mathcal{V}_f$  defines the fluid mass that is transferred from the mixture to the fluid-only layer.

The conservation of the total momentum is written

$$\rho_f \mathcal{V}_f (u - u_f) + (T_s + T_{f_m}) \tilde{N}_X = T_f \tilde{N}_X.$$

The energy balance through the interface yields the stress transfer condition

$$T_s \tilde{N}_X = \left( \frac{\rho_f}{2} \left( (u - u_f) \cdot \frac{\tilde{N}_X}{|\tilde{N}_X|} \right)^2 + \left( (T_{f_m} \tilde{N}_X) \cdot \frac{\tilde{N}_X}{|\tilde{N}_X|^2} - p_{f_m} \right) \frac{\varphi^*}{1 - \varphi^*} \right) \tilde{N}_X.$$

These conditions are completed by a Navier fluid friction condition

$$\left( \frac{T_{f_m} + T_f}{2} \tilde{N}_X \right)_\tau = -k_i (u_f - u)_\tau.$$



# Fluid pore pressure

in thin layer depth-averaged models

- From vertical momentum conservation

\* Fluid:  $\varepsilon \rho_f (1 - \varphi) (\cancel{\partial_t u^z} + \cancel{u^{\mathbf{x}} \cdot \nabla_{\mathbf{x}} u^z} + u^z \partial_z u^z) =$   
 $-(1 - \varphi) \partial_z p_{f_m} - g \cos \theta \rho_f (1 - \varphi) - \beta (u^z - v^z) - \cancel{\varepsilon \nabla_{\mathbf{x}} \cdot T_{f_m}^{\mathbf{x}z}}$

\* Solid:  $\varepsilon \rho_s \varphi (\cancel{\partial_t v^z} + \cancel{v^{\mathbf{x}} \cdot \nabla_{\mathbf{x}} v^z} + v^z \partial_z v^z) =$   
 $-\partial_z p_s - \varphi \partial_z p_{f_m} - g \cos \theta \rho_s \varphi + \beta (u^z - v^z) - \cancel{\varepsilon \nabla_{\mathbf{x}} \cdot T_s^{\mathbf{x}z}}$

→  $p_{f_m} = \rho_f g \cos \theta (b + h_m + h_f - z) + \widetilde{p_{f_m}^e}$

→  $p_s = (\rho_s - \rho_f) g \cos \theta \bar{\varphi} (b + h_m - z) - \widetilde{p_{f_m}^e}$

using the closure equation  $\nabla \cdot v = K \dot{\gamma} (\varphi - \varphi_c)$

- Non-hydrostatic fluid pressure



$$\widetilde{p_{f_m}^e} = \frac{\bar{\beta}}{1 - \bar{\varphi}} h_m (\overline{u^{\mathbf{x}}} - \overline{v^{\mathbf{x}}}) \cdot \nabla_{\mathbf{x}} b - \frac{\bar{\beta}}{1 - \bar{\varphi}} \frac{h_m^2}{2} \left( \nabla_{\mathbf{x}} \cdot (\overline{u^{\mathbf{x}}} - \overline{v^{\mathbf{x}}}) + \frac{K \bar{\gamma} (\bar{\varphi} - \varphi_c)}{1 - \bar{\varphi}} \right)$$

• **Bouchut, Fernandez-Nieto, Mangeney, Narbona-Reina's model**

$$\begin{aligned} \rho_s \bar{\varphi} (\partial_t v + v \nabla_{\mathbf{x}} v) &= -(\rho_s - \rho_f) g \cos \theta \frac{h_m}{2} \nabla_{\mathbf{x}} \bar{\varphi} + (1 - \bar{\varphi}) \nabla_{\mathbf{x}} \widetilde{p_{f_m}^e} \\ &\quad - g \cos \theta \bar{\varphi} (\rho_s \nabla_{\mathbf{x}} (b + h_m)) \\ &\quad - \text{sign}(v) (\tan \delta + K(\bar{\varphi} - \varphi_c)) \frac{1}{h_m} \left( (\rho_s - \rho_f) g \cos \theta \bar{\varphi} h_m - \widetilde{p_{f_m}^e} \right) \\ &\quad + \bar{\beta} (u - v) - \rho_s g \sin \theta \bar{\varphi} (1, 0)^t. \end{aligned}$$

$$\begin{aligned} \rho_f (1 - \bar{\varphi}) (\partial_t u + u \nabla_{\mathbf{x}} u) &= -\rho_f g \cos \theta (1 - \bar{\varphi}) \nabla_{\mathbf{x}} (b + h_m) - (1 - \bar{\varphi}) \nabla_{\mathbf{x}} \widetilde{p_{f_m}^e} \\ &\quad - \bar{\beta} (u - v) - (1 - \bar{\varphi}) \rho_f g \sin \theta (1, 0)^t \\ &\quad - \frac{1}{h_m} \left( \left( \frac{\rho_f \mathcal{V}_f}{2} - \alpha \right) (\bar{u}_{f_j}^x - u) \right) \end{aligned}$$

$$\widetilde{p_{f_m}^e} = \frac{\bar{\beta}}{1 - \bar{\varphi}} h_m (u - v) \cdot \nabla_{\mathbf{x}} b - \frac{\bar{\beta}}{1 - \bar{\varphi}} \frac{h_m^2}{2} \left( \nabla_{\mathbf{x}} \cdot (u - v) + \frac{K \bar{\gamma} (\bar{\varphi} - \varphi_c)}{1 - \bar{\varphi}} \right)$$

• **Iverson and George's model**

Isotropy of normal stress

$$\begin{aligned} \bar{\rho}_m (\partial_t v_m + v_m \nabla_{\mathbf{x}} v_m) &= -\bar{\rho} g \cos \theta \nabla_{\mathbf{x}} (b + h_m) + (k - 1) \nabla_{\mathbf{x}} \widetilde{p_{f_m}^e} \\ &\quad - \text{sign}(v_m) (\tan(\delta + \psi)) \frac{1}{h_m} \left( (\rho_s - \rho_f) g \cos \theta \bar{\varphi} h_m - \widetilde{p_{f_m}^e} \right) \end{aligned}$$

$$\partial_t \widetilde{p_{f_m}^e} - \nabla \cdot \left( \frac{\kappa}{\alpha \mu} \nabla \widetilde{p_{f_m}^e} \right) = -\frac{\dot{\gamma} \tan \psi}{\alpha} + \partial_t (\sigma - \rho_f g (h - z) \cos \theta)$$

Our thin-layer averaged model has three scalar equations on  $h_m$ ,  $h_f$ ,  $\varphi$  instead of two :

$$\begin{aligned}\partial_t(\bar{\varphi}h_m) + \nabla_x \cdot (\bar{\varphi}h_m\bar{v}^x) &= 0, \\ \partial_t((1 - \bar{\varphi})h_m + h_f) + \nabla_x \cdot ((1 - \bar{\varphi})h_m\bar{u}^x + h_f\bar{u}_f^x) &= 0, \\ \partial_t\bar{\varphi} + \bar{v}^x \cdot \nabla_x\bar{\varphi} &= -\bar{\varphi}\bar{\Phi}.\end{aligned}$$

with

$$\bar{\Phi} = K\bar{\gamma}(\bar{\varphi} - \bar{\varphi}_c).$$

It satisfies

- conservation of granular and fluid mass
- conservation of total momentum
- decrease of energy
- dilatancy with excess pore pressure, and fluidisation/stiffening of the granular material
- convergence to hydrostatic equilibrium in case of no external forces
- diffusion term on the relative velocity similar to the George-Iverson model

Numerical simulations in progress !

Open problem : include viscoplastic rheology with yield stress

The modeling of **wet granular materials** leads to several very difficult issues

- The used (incompressible) viscoplastic laws are not justified from microscopic laws
- Need to write a geophysically and mathematically relevant rheology for **compressible viscoplastic materials with yield stress and dilatancy**
- Need to derive associated thin-layer models

The modeling of **wet granular materials** leads to several very difficult issues

- The used (incompressible) viscoplastic laws are not justified from microscopic laws
- Need to write a geophysically and mathematically relevant rheology for **compressible viscoplastic materials with yield stress and dilatancy**
- Need to derive associated thin-layer models

*We're nothing, and nothing will help us  
Maybe we're lying, then you'd better not stay  
But we could be safer, just for one day*

D. Bowie "Heroes"