Motion of a massive particle in a rarefied gas.

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Question : can we say something about the macroscopic motion of the molecule?

The microscopic dynamics





Admissible configurations

- Positions of the atoms $X_N := (x_1, \dots, x_N)$ $\forall i \neq j, \quad |x_i - x_j| > \varepsilon$
- Position and orientation of the molecule (X, Θ)

$$\forall i \quad d(x_i, X + \frac{\varepsilon}{\alpha} R_{\Theta} \bar{\Sigma}) > \varepsilon$$

The surface of the reference convex body $\partial \overline{\Sigma}$ is parametrized by $\overline{\sigma}$.





Newton's laws

- Velocities of the atoms $V_N := (v_1, \ldots, v_N)$
- Velocity of the center of mass and angular velocity of the molecule $(V, \hat{\Omega})$

are constant except at collisions.

Collision laws for the atoms

$$v'_{i} := v_{i} - \frac{1}{\varepsilon^{2}}(v_{i} - v_{j}) \cdot (x_{i} - x_{j}) (x_{i} - x_{j})$$
$$v'_{j} := v_{j} + \frac{1}{\varepsilon^{2}}(v_{i} - v_{j}) \cdot (x_{i} - x_{j}) (x_{i} - x_{j})$$





Collision laws for the molecule

- The collision produces a force f in the direction n which is a Dirac mass in time \rightarrow jump conditions
- The total energy is conserved.

$$\begin{split} v'-v &= \frac{2}{A+1} (V + \hat{\Omega} \wedge \frac{\varepsilon}{\alpha} r - v) \cdot n \, n \\ V'-V &= -\frac{2m}{M(A+1)} (V + \hat{\Omega} \wedge \frac{\varepsilon}{\alpha} r - v) \cdot n \, n \\ \hat{\Omega}' - \hat{\Omega} &= -\frac{2m}{(A+1)} (V + \hat{\Omega} \wedge \frac{\varepsilon}{\alpha} r - v) \cdot n \, \hat{I}^{-1} \frac{\varepsilon}{\alpha} r \wedge n \, . \end{split}$$

ith
$$A := \frac{m}{M} + m \left(\frac{\varepsilon}{\alpha}\right)^2 \left(r \times n \cdot \hat{I}^{-1}r \times n\right)$$



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Collision invariants

The following quantities are conserved

 $\mathcal{P} := mv + MV$ (total momentum)

$$\begin{split} \mathcal{E} &:= \frac{1}{2} (m|v|^2 + M|V|^2 + \hat{\Omega}\hat{I}\hat{\Omega}) \quad \text{(total energy)} \\ \hat{\mathcal{I}} &:= \hat{I} \cdot \hat{\Omega} + MV \wedge \frac{\varepsilon}{\alpha} r \quad \text{(angular momentum at the contact point)} \,. \end{split}$$

Due to the smallness of the molecule, it is natural to rescale the angular velocity and the moment of inertia : $(m)^2$

$$I := \left(\frac{\alpha}{\varepsilon}\right)^2 \hat{I} \quad \text{and} \quad \Omega := \frac{\varepsilon}{\alpha} \hat{\Omega}$$





The low density asymptotics





A statistical point of view

We are interested in the probability distribution of the molecule

$$f_N^{(1)}(t, X, V, \Theta, \Omega) := \int f_N(t, X, V, \Theta, \Omega, Z_N) dZ_N$$

where f_N satisfies the Liouville equation

$$\partial_t f_N + V \cdot \nabla_X f_N + \sum_{i=1}^N v_i \cdot \nabla_{x_i} f_N + \frac{\alpha}{\varepsilon} \Omega \cdot \nabla_{\Theta} f_N = 0$$

supplemented with reflection conditions on $\partial \mathcal{D}_N^{\varepsilon}$.





The Boltzmann-Grad scaling

The transport and collision process for the atoms have the same time scale if

$$N\varepsilon^{d-1} = 1$$

which only holds for **rarefied gases**.



N spheres of size ε on a lattice

Volume covered by one particle of velocity v during a time t : $|v|t \epsilon^{d-1}$





The BBGKY hierarchy

By Green's formula and the symmetry,

$$\begin{aligned} \partial_t f_N^{(s)} + V \cdot \nabla_X f_N^{(s)} + \sum_{i=1}^{s-1} v_i \cdot \nabla_{x_i} f_N^{(s)} + \frac{\alpha}{\varepsilon} \Omega \cdot \nabla_{\Theta} f_N^{(s)} \\ &= C_{s,s+1} f_N^{(s+1)} + D_{s,s+1} f_N^{(s+1)} \end{aligned} \qquad \text{on } \mathcal{D}_{s-1}^{\varepsilon} \end{aligned}$$

where $C_{s,s+1}$ is the boundary term describing the collision between two atoms

$$C_{s,s+1}f^{(s+1)} := (N-s+1)\varepsilon^{d-1}\sum_{i=1}^{s-1}\int f^{s+1}(\ldots,x_i+\varepsilon\nu,v_s)((v_i-v_s)\cdot\nu)d\nu dv_s$$





and $D_{s,s+1}$ holds for collisions with the molecule $D_{s,s+1}f^{(s+1)} := (N-s+1)\left(\frac{\varepsilon}{\alpha}\right)^{d-1}\sum_{i=1}^{s-1}\int f^{s+1}(\dots, X + \frac{\varepsilon}{\alpha}R_{\Theta}\bar{r} + \varepsilon R_{\Theta}\bar{n}, v_s)$ $((V + \Omega \wedge R_{\Theta}\bar{r}) - v_s) \cdot R_{\Theta}\bar{n}d\bar{\sigma}dv_s$

The normal to the collision surface in the (X, x, Θ) space is indeed given by $(-R_{\Theta}\bar{n}, R_{\Theta}\bar{n}, R_{\Theta}(\bar{r} \wedge \bar{n}))$

Both collision integrals can be split according to the sign of the integrand. We then use the scattering to express the gain part in terms of **precollisional configurations**.





Close to equilibrium

To get an equation for the motion of the molecule, we need a closure for the hierarchy. Here we will assume that **atoms are almost at equilibrium**

 $f_{N,0}(X,V,\Theta,\Omega,X_N,V_N) := M_N(V,\Omega,V_N)g_0(X,V,\Theta,\Omega)$

$$M_N(V,\Omega,V_N) = \left(\frac{\beta}{2\pi}\right)^{\frac{d}{2}(N+1) + \frac{d(d-1)}{4}} m^{\frac{dN}{2}} (\det I)^{1/2} \exp\left(-\frac{\beta}{2} \left(|V|^2 + m|V_N|^2 + \Omega \cdot I \cdot \Omega\right)\right) \frac{\mathbf{1}_{\mathcal{D}_N}}{\mathcal{Z}_N}$$

As the Gibbs measure M_N is a stationary solution to the Liouville equation, we expect this form to be **stable under the dynamics** in the low density limit.





The grazing collision limit





A weak coupling scaling

We are interested in the motion of a **big molecule surrounded by a fluid** (rarefied gas), i.e.

$$\frac{m}{M} = \alpha^{2(d-1)}, \quad \alpha << 1,$$

The molecule will therefore undergo a lot of collisions, but each one of these collisions will generate an **infinitesimal deflection**:

$$V'_n = V_n - \frac{2m}{A+1}b \quad \text{and} \quad \Omega' = \Omega - \frac{2m}{(A+1)}bI^{-1}(r \wedge n)$$

with $b = (V + \Omega \wedge r - v) \cdot n$





The Boltzmann equation

Provided that we get uniform convergence estimates in α as $\varepsilon \to 0$, the dynamics should be approximated by the **Boltzmann equation**

$$\partial_{t}g_{\alpha} + V \cdot \nabla_{X}g_{\alpha} = \frac{1}{\alpha^{d-1}} \int d\Theta \int_{\partial \bar{\Sigma}_{\alpha} \times \mathbb{R}^{d}} \left(\frac{\beta m}{2\pi}\right)^{\frac{a}{2}} e^{-\frac{\beta}{2}m|v|^{2}} \\ \left(g_{\alpha}(X, V', \Omega')\big((V' - v' + \Omega' \times R_{\Theta}\bar{r}) \cdot R_{\Theta}\bar{n}\big)_{-} - g_{\alpha}(X, V, \Omega)\big((V - v + \Omega \times R_{\Theta}\bar{r}) \cdot R_{\Theta}\bar{n}\big)_{-}\right) d\bar{\sigma}dv \,.$$

Note the **angular average** coming from the singular perturbation in the transport.





The collision term in weak form

We have now to exhibit **cancellations between the gain and loss parts** in the collision integral.

We use a **duality argument** and compute

$$\begin{split} F &:= \frac{1}{\alpha^{d-1}} \int \left(\frac{\beta m}{2\pi}\right)^{\frac{d}{2}} e^{-\frac{\beta}{2}(|V|^2 + m|v|^2 + \Omega \cdot I \cdot \Omega)} g_{\alpha}(X, V, \Omega) \big((V - v + \Omega \times r) \cdot n \big)_{-} \\ & \times \big(\varphi(X, V', \Omega') - \varphi(X, V, \Omega) \big) \, d\sigma dv dX d\Omega dV d\Theta \,. \end{split}$$

Note that because atoms are lighter, they move faster and we expect $v = O(m^{-1/2})$.





A generalized Ornstein-Uhlenbeck process

At leading order in α , the two terms cancel by **Stokes formula** $\int_{\partial \Sigma} n \cdot ed\sigma = \int_{\Sigma} \nabla \cdot edr = 0$,

$$\int_{\partial \Sigma_{\alpha}}^{J_{\Sigma_{\alpha}}} r \wedge n \cdot ed\sigma = \int_{\Sigma_{\alpha}} \nabla \cdot (e \wedge r) dr = 0.$$

We then get, for some N,K,T depending only on $\overline{\Sigma}$ $F = \left(\frac{2}{\pi\beta}\right)^{1/2} \int dX d\Omega dV e^{-\frac{\beta}{2}(|V|^2 + \Omega \cdot I \cdot \Omega)} g_{\alpha}(X,V,\Omega)$ $\times \left((VN + \Omega K) \nabla_V \varphi(X,V,\Omega) + (VK^t + \Omega T)I^{-1} \nabla_\Omega \varphi(X,V,\Omega) + \frac{2}{\beta} (\nabla_V \cdot N \cdot \nabla_V + I^{-1} \nabla_\Omega \cdot T \cdot I^{-1} \nabla_\Omega + 2\nabla_V \cdot K^t \cdot I^{-1} \nabla_\Omega) \varphi(X,V,\Omega)\right)$



Strategy of the proof





Collision trees

Solutions of the molecular dynamics can be represented by **collision trees**, with transport and scattering operators.

t₃

t₂

ECOLE NORMALE SUPERIEURE



Recollisions

Solutions of the Boltzmann equation (with precession) provide a good approximation as long as there is no **recollision** (i.e. no collision between two atoms which are not independent)

t₃

t₂



Geometric control of recollisions

• By a **geometric study** of the free transport (with precession), we can prove that recollisions are of small probability when $\varepsilon <<1$, $\alpha >> \varepsilon^{1/d}$

• We therefore **remove a small set** of bad parameters from each collision integral.

 $S(0,\epsilon/\alpha)$





X1-X7

About the size of the trees

• The truncation is admissible only for **relatively small trees** (of size at most log N).

 In Lanford's proof, the size of the trees is controlled only for very short times, by some Cauchy-Kowalewski estimate.

 Close to equilibrium, we use global a priori estimates to discard superexponential trees.





A sampling in time

Superexponential trees are negligible if $h \ll \frac{t}{\alpha^{2(d-1)}}$



The error coming from the geometric surgery is



$$C^{2^{\kappa}}\varepsilon^{1/2}$$
 with $K=\frac{t}{h}$



What can be said about macroscopic molecules?



